Description of Command and Control Networks in Coq

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**Abstract.** A command and control (C2) system can be defined as any group of individuals organized hierarchically in which higher-ranking individuals can issue directions to their subordinates with a certain goal in mind. We present a model for representation of command and control networks in the Coq proof assistant based on a tree data structure. Our model utilizes Coq’s implementation of data structures and includes examples of how to define functions and properties that may be relevant in a C2 system.

**Keywords:** Coq, proof assistant, command and control, tree data structure

1. Introduction

The term “command and control” can be used in various contexts, with one common example of its use being in reference to a military system. More generally speaking, a command and control network can be defined as any system in an individual or entity may issue directions to another with the aim of achieving a certain objective. There are countless ways in which a C2 system may be organized, but the work described here concerns itself specifically with systems organized as a hierarchy, with individuals subordinate to others which may give them directions.

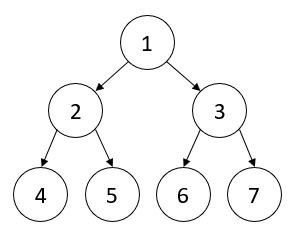
Naturally, there is a variety of algorithms, properties and functions that may be relevant when discussing a C2 system. For example, knowing which individual ranks the highest in the network (i.e. the leader) we may be interested in knowing who its direct subordinates are, and out of these, which one should take control in the event that the leader is eliminated. Alternately, we may want to guarantee that the way the network is organized makes sense, such as by not having two individuals be subordinate to each other (no cycles). We may also want to make sure that there are no “orphaned” individuals in the network, i.e., that every node other than the leader is subordinate to some other node.

Our work described in this paper is a model for generic representation of a C2 network in the Coq proof assistant. We have done this by first establishing how to represent the network itself—specifically, as a tree data structure—followed by the definition of relevant variables and functions, and lastly, how these functions are implemented. Our goal is to both help Coq developers seeking some insight into certain types of algorithms are done in the proof assistant and to provide some useful tools for Coq projects dealing with anything related to C2 or hierarchy.

1. Representation of a Network in Coq
   1. Basic Concepts

Firstly, let us establish what networks mean in this context. A network is a group of nodes, with each node being an individual in a C2 system. The hierarchy between these individuals is represented by a connected and acyclic graph, i.e., a tree. The root of the tree represents the leader in our C2 system, with each edge indicating which individuals are direct subordinates of which.

By definition, we have established that each individual in the network (other than the leader) has only one direct superior. However, an individual can have any number of direct subordinates. Additionally, every network has one and only one leader. Figure 1.2 shows an example of a graph representing such a system, with individual 1 as the leader, 2 and 3 as its direct subordinates, and so on.



**Fig. 1.** Directed graph representing the hierarchy in a command and control network.

* 1. Defining a Network

Now, let us describe how to represent these C2 graphs in Coq. To do so, we need to define a data structure. Coq provides us with the means to do so via the **Structure** operator. The Coq code containing the main body of the structure we will define follows.

Require Import Coq.Lists.List.

Section nets.

Structure net : Type := {

nodes : nat ;

leader : nat ;

superior : list (nat \* nat) ;

second\_in\_command : nat := get\_second superior leader ;

parent : nat -> nat := get\_parent superior ;

children : nat -> list nat := get\_children superior ;

is\_parent : nat -> nat -> Prop := is\_parent\_func superior;

is\_parent\_bool : nat -> nat -> bool := is\_parent\_func\_bool superior;

node\_order : nat -> nat := get\_node\_order ;

sorted\_superior : list (nat \* nat) := sort superior ;

node\_level : nat -> nat := get\_level superior ;

}.

Here, we have defined a command and control network as a structure with a single leader node and a set of nodes subordinate to this leader, who in turn can have their own subordinates, and so on. The objects and functions that make up this structure are:

The number of nodes in the network, defined here as **nodes**, which are represented by a single natural number. By definition, nodes in our model are numbered individually starting from 1 without skipping any number, so nodes will also always be equal to the highest node value in a particular network. A structure with a value of 10 assigned to the nodes field, for example, will have a total of nodes numbered from 1 to 10.

**leader** tells us the index of the node which is the network’s leader, equivalent to the root of the graph.

**superior** tells us which nodes are direct subordinates of which others. This field is a list of pairs of natural numbers representing our graph, which each pair being a single edge containing the index of two nodes (parent and child). We assume that the numbers contained within these pairs are consistent with the node values defined by nodes.

**second-in-command** is a function which tells us which node in the network is the second-in-command of the current leader and the one that should replace the current leader if necessary. It is defined as the first subordinate of the leader node, as we will describe in more detail ahead.

**parent** and **children** are functions that receive a single node (natural number) as an argument and, respectively, return the index of the superior/parent node or a list of indices indicating the children/subordinates of the node.

Note that all we have defined so far are the headers of the functions in our structure, which tell us what types they receive as arguments and which types they should return. For example, look at the definition of parent here:

parent : nat -> nat := get\_parent superior ;

We are informing Coq after the : operator that the function receives a single natural number value and also returns a natural number value. After the := operator, we tell Coq how the computation of the return value is to be done—in this case, by calling a function named get\_parent which w will define later outside of our data structure. Since this function will require the values stored in superior, the list of edges, we give that as an argument here as well.

Now, let us get into the actual implementation of these individual functions.

The **second-in-command** function, as stated, tells us which node is considered the highest-ranking subordinate of the current leader and the one that should be made the leader if the current one needs to be replaced. \*\*\*

Fixpoint get\_second (edges : list (nat \* nat)) (leader : nat) : nat :=

match edges with

| (a,b) :: edges' => if (Nat.eqb a leader)

then b

else get\_second edges' leader

| nil => 0

end.

The **get\_parent** function receives one node and needs to tell us its parent node. To do this, it recursively searches through the list of edges, comparing the second number in each one (the child node, or b) with the given value until it finds a match. When that happens, the first value of the pair (the parent node, or a) is returned. Since our model already assumes that the network is defined with each node having only one parent, there is no need to search through the rest of the list after a match is found.

Should the function finish searching the list without finding an edge whose target node matches the given value, it returns 0 by default, indicating that the node has no parent. This should happen only when the value given is the leader, i.e., the root node.

Fixpoint get\_parent (edges : list (nat \* nat)) (node : nat) : nat :=

match edges with

| (a,b) :: edges' => if (Nat.eqb node b) then a

else get\_parent edges' node

| nil => 0

end.

The **get\_children** function operates similarly to get\_parent. However, since a node can have any number of children, this function needs to return a list of natural numbers. Once again, the function recursively calls itself to Search through the list of edges, this time comparing the given value with the parent node, **a**, in each edge. Once a match is found, we append the child value **b** to the list that will be our final product and continue searching via recursion, as you can see below. At the end of the run, we will have searched through every edge and have the complete list of children of the given node.

If the node has no children, an empty list value **nil** will be returned.

Fixpoint get\_children (edges : list (nat \* nat)) (node : nat) : list nat :=

match edges with

| (a,b) :: edges' => if (Nat.eqb node a) then b :: get\_children edges' node

else get\_children edges' node

| nil => nil

end.

We have also defined functions that tell us if two given nodes are parent and child to each other. This question of “if” can be answered in Coq by two different types, proposition (Prop) or boolean (bool). For comparison’s sake, we have included two different “is parent” functions, one of each of these. As you will see, they are mostly similar but with some differences in which operators are used.

Note the importance of capitalization in the names of certain constants here. In Coq, **False** and **True** with capital letters are interpreted as values of type **Prop**, while **false** and **true** are interpreted as values of type **bool**.

Fixpoint is\_parent\_func (edges : list (nat \* nat)) (a b : nat) : Prop :=

match edges with

| nil => False

| h :: t => h = (a,b) \/ is\_parent\_func t a b

end.

Fixpoint is\_parent\_func\_bool (edges : list (nat \* nat)) (a b : nat) : bool :=

match edges with

| nil => false

| h :: t => ((Nat.eqb (fst h) a) && (Nat.eqb (snd h) b)) || is\_parent\_func\_bool t a b

end.

Next, let us look at the **get\_level** function. This function tells us the level of a node in the hierarchy. The leader’s level is by definition 1, while the level of its direct subordinates is 2, and so on.

Fixpoint get\_level\_run\_once (edges : list (nat \* nat)) (node\_and\_depth : nat \* nat) : nat \* nat :=

match edges with

| (a,b) :: edges' => if (Nat.eqb b (fst node\_and\_depth)) then get\_level\_run\_once edges' (a, (snd node\_and\_depth) + 1)

else get\_level\_run\_once edges' ((fst node\_and\_depth), (snd node\_and\_depth))

| nil => ((fst node\_and\_depth), (snd node\_and\_depth))

end.

Definition get\_level\_run\_once\_result (edges : list (nat \* nat)) (node : nat) : nat \* nat :=

get\_level\_run\_once edges (node, 1).

Fixpoint get\_level\_run\_all (edges : list (nat \* nat)) (times : nat) (node\_and\_depth : nat \* nat) : nat \* nat :=

match times with

| 0 => ((fst node\_and\_depth), (snd node\_and\_depth))

| S n => get\_level\_run\_all edges n (fst (get\_level\_run\_once edges node\_and\_depth),

snd (get\_level\_run\_once edges node\_and\_depth))

end.

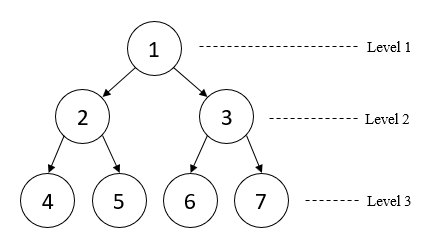
Definition get\_level (edges : list (nat \* nat)) (node : nat) : nat :=

snd (get\_level\_run\_all edges (length edges) (node, 1)).

So far, we have only given an abstract description of what our networks in Coq are like. In the next section, we will see an example of **get\_level** and other functions applied to actual network instances with defined elements.

* 1. Defining a Network Instance

Revisiting the network example shown earlier in Fig. 1, we can see that it has three different levels of hierarchy.



**Fig. 2.** Example of a network with three hierarchy levels.

To create this particular instance of a network in Coq, we use the following definition:

Definition net\_1 : net := Build\_net 7 1

((1 , 2) :: (1 , 3) :: (2 , 4) :: (2 , 5) :: (3 , 6) :: (3 , 7) :: nil)

* 1. Defining Properties

Now, we can move on to using the appropriate tools in Coq to define properties that a network and its elements must have. To start with a simple example, we will define the property “in any network, the leader must be one of its elements”.

As mentioned before, the list of nodes in a network is represented by a single natural number telling us how many nodes there are, with the assumption that they are all individually numbered from 1 to the stated value. Therefore, a value of 10 in this field, for example, tells us that we have a network with 10 nodes numbered 1 to 10. Thus, in order to define that the leader is always a valid node, all we need to do is inform Coq that its index is contained in that interval.

In other words, we want to tell Coq that:

This is done in Coq fairly simply:

Definition leader\_is\_in\_net := forall n : net, leader n <= nodes n.

Another property we can define is the affirmation that no node can be its own superior. To do this, we will use the **superior** element, which, as already shown, is a list of pairs of numbers representing each edge of the graph, i.e., the indices of a parent node and child node. Basically, what we want to say is that none of these pairs contain the same number twice.

Definition no\_self\_superior :=

forall (n : net) (i : nat), fst (nth i (superior n) (0,0)) <> snd (nth i (superior n) (0,0)).

**superior n** is the superior function applied to any given network **n**, which returns the list of pairs

**nth i (superior n) (0,0)**, for any value of **i**, applies the function **nth** to return any element of **superior n**, that is, any edge. For context, the function’s third argument, given here as the pair (0,0), is simply a default return value that we are telling **nth** it should return in case the stated value of **i** is invalid for the given list or the list is empty.

**fst** e **snd** are functions that return the first and second number in a pair, respectively, and the **<>** operator states that two values are different. Therefore, what we are defining is that the list of edges cannot contain an element **(a,b)** in which **a** and **b** are equal.

By applying these same principles, we can define other things about the elements of a C2 network. Suppose, for example, that we want to define that the leader is always the root, i.e., that there is no edge in the graph for which the leader is in the child node position. This is done similarly to the properties we have already defined, this time with the negated **exists** operator.

Definition leader\_is\_top := forall (n : net),

~ exists i : nat, snd (nth i (superior n) (0,0)) = leader n.

Lastly, we can also define functions that can be applied to the elements of a network.

Fixpoint num\_children (edges : list (nat \* nat)) (node count : nat) : nat :=

match edges with

| nil => count

| (a,b) :: edges' => if (Nat.eqb a node)

then num\_children edges' node (count+1)

else num\_children edges' node count

end.

1. Conclusion

We hope that the examples of structures, functions and properties described here can be of assistance to Coq developers in search of a general model for a command and control system or any system in which the concept of hierarchy may be relevant, as well as developers simply seeking some insight into how Coq operates.

We also intend to continue development of this model where possible by expanding it to include more complex functions and properties, particularly ones based on the ones already established here.

References

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